



Member Full Version



all data without guarantee - Accuracy: +/-10%

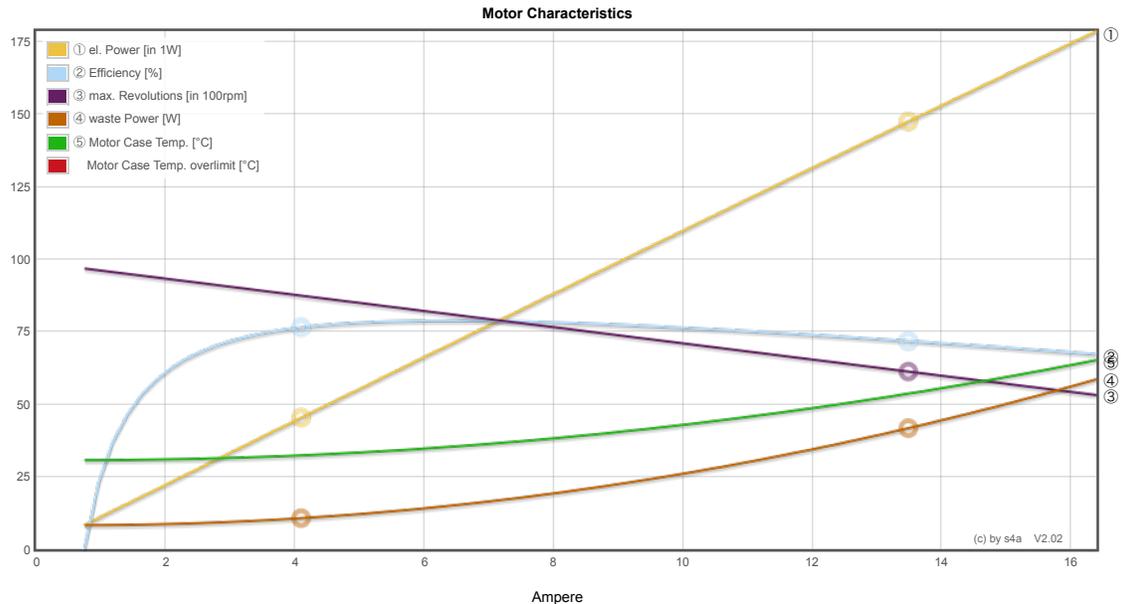
xcopterCalc - Multicopter Calculator

Help | Language: english

<b>General</b>	Motor Cooling: <input type="text" value="medium"/>	# of Rotors: <input type="text" value="6"/>	Model Weight: <input type="text" value="2000"/> g <input type="text" value="70.5"/> oz	<input type="text" value="incl. Drive"/>	Field Elevation: <input type="text" value="500"/> m ASL <input type="text" value="1640"/> ft ASL	Air Temperature: <input type="text" value="25"/> °C <input type="text" value="77"/> °F	Pressure (QNH): <input type="text" value="1013"/> hPa <input type="text" value="29.91"/> inHg	
<b>Battery Cell</b>	Type (Cont. / max. C) - charge state: <input type="text" value="LiPo 5000mAh - 30/45C"/> - <input type="text" value="normal"/>	Configuration: <input type="text" value="3"/> S <input type="text" value="2"/> P	Cell Capacity: <input type="text" value="5000"/> mAh	Total Capacity: <input type="text" value="10000"/> mAh	Resistance: <input type="text" value="0.0034"/> Ohm	Voltage: <input type="text" value="3.7"/> V	C-Rate: <input type="text" value="30"/> C cont. <input type="text" value="45"/> C max	Weight: <input type="text" value="141"/> g <input type="text" value="5"/> oz
<b>Controller</b>	Type: <input type="text" value="max 30A"/>	cont. Current: <input type="text" value="30"/> A	max. Current: <input type="text" value="30"/> A	Resistance: <input type="text" value="0.008"/> Ohm	Weight: <input type="text" value="40"/> g <input type="text" value="1.4"/> oz			
<b>Motor</b>	Manufacturer - Type (Kv): <input type="text" value="E-flite"/> <input type="text" value="Park 450 (890)"/> <input type="button" value="search..."/>	KV (w/o torque): <input type="text" value="890"/> rpm/V	no-load Current: <input type="text" value="0.7"/> A @ <input type="text" value="10"/> V	Limit (up to 15s): <input type="text" value="18"/> A	Resistance: <input type="text" value="0.2"/> Ohm	Case Length: <input type="text" value="27"/> mm <input type="text" value="1.06"/> inch	# mag. Poles: <input type="text" value="12"/>	Weight: <input type="text" value="72"/> g <input type="text" value="2.5"/> oz
<b>Propeller</b>	Type - yoke twist: <input type="text" value="custom"/> - <input type="text" value="0°"/>	Diameter: <input type="text" value="11"/> inch	Pitch: <input type="text" value="4.7"/> inch	# Blades: <input type="text" value="2"/>	PConst: <input type="text" value="1.3"/>	Gear Ratio: <input type="text" value="1"/> : <input type="text" value="1"/>	<input type="button" value="calculate"/>	

**Remarks:**

Battery	Motor @ Optimum Efficiency	Motor @ Maximum	Motor @ Hover	Total Drive
Load: 8.20 C	Current: 6.12 A	Current: 13.67 A	Current: 4.16 A	Drive Weight: 1670 g
Voltage: 10.68 V	Voltage: 10.86 V	Voltage: 10.57 V	Voltage: 10.94 V	58.9 oz
Rated Voltage: 11.10 V	Revolutions*: 8034 rpm	Revolutions*: 5760 rpm	Throttle (linear): 52 %	All-up Weight: 2000 g
Flight Time: 7.3 min	electric Power: 66.5 W	electric Power: 144.5 W	electric Power: 45.5 W	70.5 oz
Mixed Flight Time: 9.5 min	mech. Power: 52.3 W	mech. Power: 102.2 W	mech. Power: 34.9 W	add. Payload: 1005 g
Hover Flight Time: 20.4 min	Efficiency: 78.7 %	Efficiency: 70.7 %	Efficiency: 76.6 %	35.4 oz
Weight: 846 g		est. Temperature: 54 °C	est. Temperature: 32 °C	Current @ Hover: 24.98 A
29.8 oz		129 °F	90 °F	P(in) @ Hover: 277.3 W
				P(out) @ Hover: 209.4 W
				Efficiency @ Hover: 75.5 %
				Current @ max: 82.01 A
				P(in) @ max: 910.3 W
				P(out) @ max: 613.2 W
				Efficiency @ max: 67.4 %



**Important Note:** Before flight recheck your max. current! If your Current, el. Power or RPM are over the manufacturers limits your motor, controller and/or battery may take damage! **Verify before flight by measurement!** [generate link >](#)

for printing use Landscape format  
 \* The manufacturer limitation is NOT monitored  
 \*\* Testdata with reduced accuracy

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